

```
In [1]: using Plots
```

```
In [7]: plotly()
```

```
Out[7]: Plots.PlotlyBackend()
```

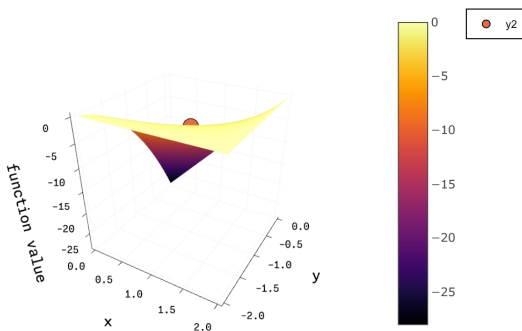
hint for 問 3 (1)

```
In [2]: X = 0:0.01:2
Y = -2:0.01:0
Z = [ 3*x^2*y + x*y for x in X, y in Y ]
```

```
Out[2]: 201x201 Matrix{Float64}:
-0.0      -0.0      -0.0      -0.0      ... -0.0      -0.0      0.0
-0.0206  -0.020497 -0.020394 -0.020291 -0.000206 -0.000103 0.0
-0.0424  -0.042188 -0.041976 -0.041764 -0.000424 -0.000212 0.0
-0.0654  -0.065073 -0.064746 -0.064419 -0.000654 -0.000327 0.0
-0.0896  -0.089152 -0.088704 -0.088256 -0.000896 -0.000448 0.0
-0.115   -0.114425 -0.11385  -0.113275 ... -0.00115  -0.000575 0.0
-0.1416  -0.140892 -0.140184 -0.139476 -0.001416 -0.000708 0.0
-0.1694  -0.168553 -0.167706 -0.166859 -0.001694 -0.000847 0.0
-0.1984  -0.197408 -0.196416 -0.195424 -0.001984 -0.000992 0.0
-0.2286  -0.227457 -0.226314 -0.225171 -0.002286 -0.001143 0.0
-0.26    -0.2587  -0.2574  -0.2561  ... -0.0026  -0.0013  0.0
-0.2926  -0.291137 -0.289674 -0.288211 -0.002926 -0.001463 0.0
-0.3264  -0.324768 -0.323136 -0.321504 -0.003264 -0.001632 0.0
⋮
-25.2126 -25.0865  -24.9605  -24.8344  ... -0.252126 -0.126063 0.0
-25.46   -25.3327 -25.2054  -25.0781  ... -0.2546  -0.1273  0.0
-25.7086 -25.5801 -25.4515  -25.323  ... -0.257086 -0.128543 0.0
-25.9584 -25.8286 -25.6988  -25.569  ... -0.259584 -0.129792 0.0
-26.2094 -26.0784 -25.9473  -25.8163 -0.262094 -0.131047 0.0
-26.4616 -26.3293 -26.197  -26.0647 -0.264616 -0.132308 0.0
-26.715  -26.5814 -26.4478  -26.3143 ... -0.26715  -0.133575 0.0
-26.9696 -26.8348 -26.6999  -26.5651 -0.269696 -0.134848 0.0
-27.2254 -27.0893 -26.9531 -26.817  -0.272254 -0.136127 0.0
-27.4824 -27.345  -27.2076  -27.0702 -0.274824 -0.137412 0.0
-27.7406 -27.6019 -27.4632 -27.3245 -0.277406 -0.138703 0.0
-28.0    -27.86   -27.72   -27.58   ... -0.28    -0.14    0.0
```

```
In [13]: surface(X, Y, Z, xlabel = "x", ylabel = "y", zlabel = "function value" )
scatter!( [1.0], [-1.0], [-4])
```

```
Out[13]:
```



hint for 問 4 (3)

```
In [1]: using SymPy
@syms t w
```

```
Out[1]: (t,)
```

```
In [3]: eq1 = cos(t)
eq2 = t^2
eq3 = exp( eq1^2 * eq2 )
```

```
Out[3]: et2 cos2(t)
```

```
In [5]: diff( eq3, t )
```

```
Out[5]: (-2t2 sin(t) cos(t) + 2t cos2(t)) et2 cos2(t)
```

hint for 問 5 (3)

```
In [8]: f = SymFunction("f")
```

```
Out[8]: f
```

```
In [12]: eq1 = 2t - 3w
eq2 = t - 5w
diff( f(eq1, eq2), t )
```

```
Out[12]: 2 ∂f(ξ1, t - 5w) |ξ1=2t-3w + ∂f(2t - 3w, ξ2) |ξ2=t-5w
```

```
In [13]: diff( f(eq1, eq2), w )
```

```
Out[13]: -3 ∂f(ξ1, t - 5w) |ξ1=2t-3w - 5 ∂f(2t - 3w, ξ2) |ξ2=t-5w
```

hint for 問 8 (1)

```
In [14]: @syms r
```

```
Out[14]: (r,)
```

```
In [15]: eq1 = r * cos(t)
eq2 = r * sin(t)
diff( f(eq1, eq2), r )
```

```
Out[15]: sin(t) ∂f(r cos(t), ξ2) |ξ2=r sin(t) + cos(t) ∂f(ξ1, r sin(t)) |ξ1=r cos(t)
```

```
In [16]: diff( f(eq1, eq2), t )
```

```
Out[16]: -r sin(t) ∂f(ξ1, r sin(t)) |ξ1=r cos(t) + r cos(t) ∂f(r cos(t), ξ2) |ξ2=r sin(t)
```

```
In [ ]:
```